# Challenges for Using Impact Regularizers to Avoid Negative Side Effects

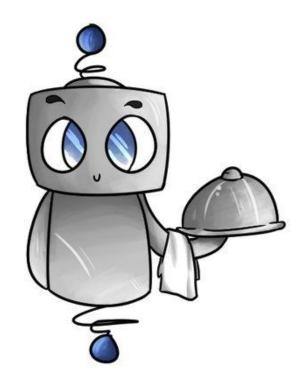
David Lindner, Kyle Matoba, Alexander Meulemans





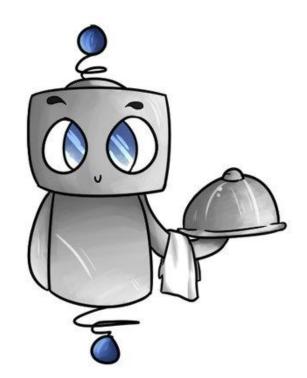
# Agents and side effects

Agents fulfill tasks by maximizing cumulative reward



# Agents and side effects

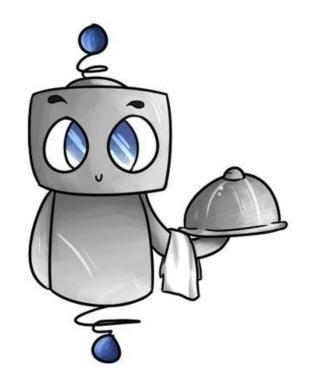
- Agents fulfill tasks by maximizing cumulative reward
- - O What should the agent not do?
- Side effects



# Agents and side effects

- Agents fulfill tasks by maximizing cumulative reward
- - O What should the agent do?
- > Side effects
- ▶ Impact regularizers

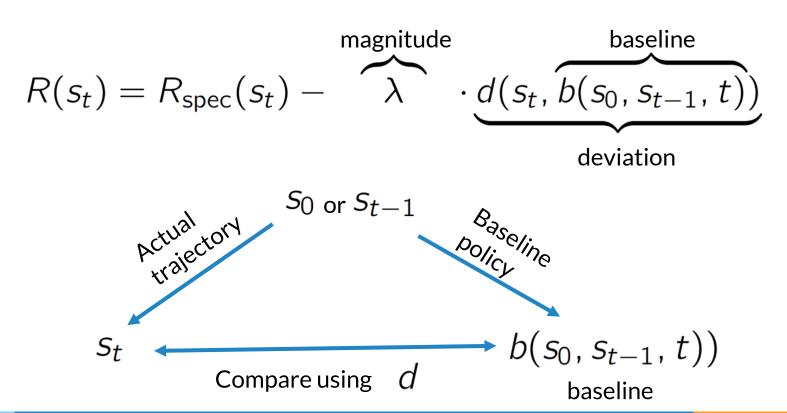
$$R(s) = R_{\text{spec}}(s) + R_{\text{IR}}(s)$$



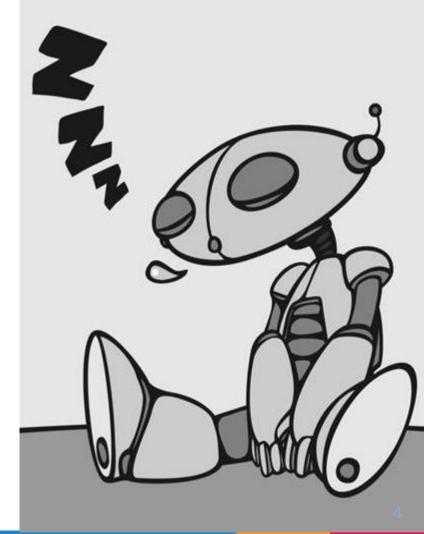
# Impact Regularizers

$$R(s_t) = R_{\mathrm{spec}}(s_t) - \lambda \cdot d(s_t, b(s_0, s_{t-1}, t))$$

# Impact Regularizers



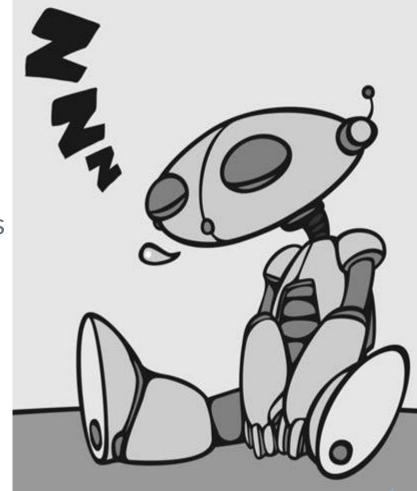
# Baseline



## Baseline

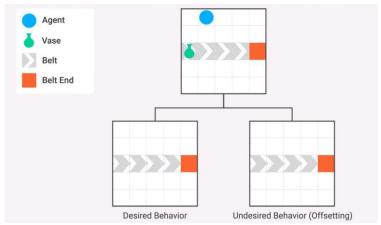
#### Problems with inaction baseline

- Offsetting



# Offsetting

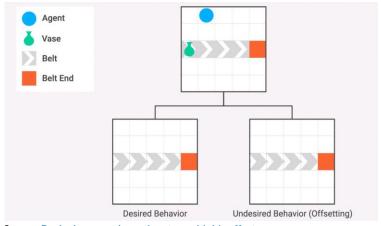
#### Undesirable offsetting



Source: Designing agent incentives to avoid side effects

# Offsetting

#### Undesirable offsetting



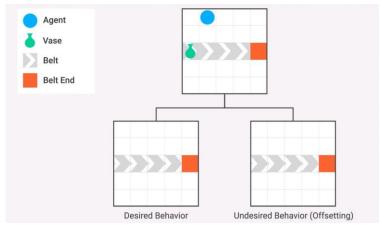
Source: Designing agent incentives to avoid side effects

#### Desirable offsetting



# Offsetting

#### Undesirable offsetting



Source: Designing agent incentives to avoid side effects

Consequence of completing the task



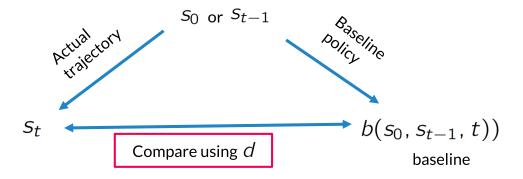
#### Desirable offsetting



Instrumental towards achieving the task

### Deviation measure

How much should a deviation from the baseline be penalized?

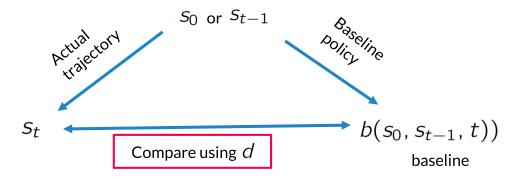


#### Deviation measure

How much should a deviation from the baseline be penalized?

Problems with current deviation measures

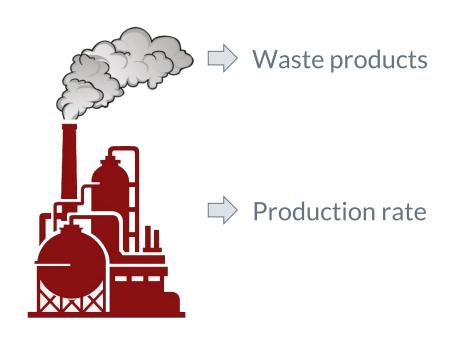
- Positive, neutral and negative side effects
- ▶ Rollout policy



# Positive, neutral and negative side effects

Not all impact is equally negative!

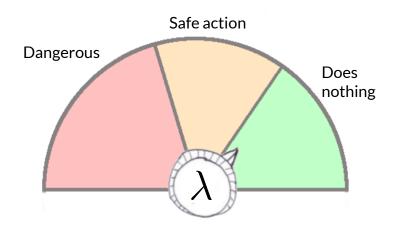
Suboptimal solutions if notion of 'value' is omitted



Optimize reaction path

# Tuning regularization magnitude

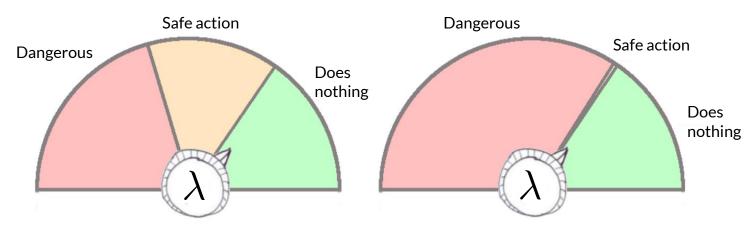
$$R(s_t) = R_{\text{spec}}(s_t) - \lambda \cdot d(s_t, b(s_0, s_{t-1}, t))$$



Source: Armstrong & Levenstein 2017

# Tuning regularization magnitude

$$R(s_t) = R_{\text{spec}}(s_t) - \lambda \cdot d(s_t, b(s_0, s_{t-1}, t))$$



Source: Armstrong & Levenstein 2017

# Ways forward

- Causal framing of offsetting
- Probabilities instead of counterfactuals
- Improved Human-Computer interaction



